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Mathematical Background

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Outline











Outline



2 Analysis

- Probability and Statistics
- Convex Optimization



Vector and Matrix

Scalar

$\pmb{x} \in \mathbb{R}$

Vector

 $\mathbf{x} \in \mathbb{R}^d$

Matrix

$$X = [\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n] \in \mathbb{R}^{d \times n}, \text{ where } \mathbf{x}_i \in \mathbb{R}^d$$
$$X = [\mathbf{z}_1^\top; \mathbf{x}_2^\top; \dots; \mathbf{z}_d^\top] \in \mathbb{R}^{d \times n}, \text{ where } \mathbf{z}_i \in \mathbb{R}^n$$



Vector and Matrix

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Vector and Matrix

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|--------|--|
| | |

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Matrix Product

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$$X = [\mathbf{x}_1, \dots, \mathbf{x}_n], Y = [\mathbf{y}_1, \dots, \mathbf{y}_n] \in \mathbb{R}^{d \times n}$$

$$XY^\top = \sum_{i=1}^n \mathbf{x}_i \mathbf{y}_i^\top \in \mathbb{R}^{d \times d}$$

Outer Product

• Vectors $\mathbf{x}, \mathbf{y} \in \mathbb{R}^d$

$$\mathbf{x}\mathbf{y}^{ op} \in \mathbb{R}^{d imes d}$$

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$$\langle \mathbf{x}, \mathbf{y} \rangle = \mathbf{x}^\top \mathbf{y} = \mathbf{y}^\top \mathbf{x} = \sum_{i=1}^d x_i y_i$$

$$\langle X, Y \rangle = \operatorname{trace}(X^{\top}Y) = \operatorname{trace}(Y^{\top}X) = \sum_{\substack{i,j, i \in \mathbb{Z}}} X_{ij}Y_{ij} = \sum_{\substack{i \in \mathbb{Z}}} \langle \mathbf{x}_i, \mathbf{y}_i \rangle$$

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Rank

Linear Independence

The vectors $\mathbf{x}_1, \ldots, \mathbf{x}_n$ are said to be linearly independent if the equation

$$\sum_{i=1}^{n} \mathbf{x}_i \alpha_i = \mathbf{0}$$

can only be satisfied by $\alpha_1 = \alpha_2 = \cdots = \alpha_n = 0$. Otherwise, they are linearly dependent.

Rank

The rank of a matrix X is the dimension of the vector space spanned by its columns. This is the same as the dimension of the space spanned by its rows. It is also the maximal number of linearly independent columns or rows of X.



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Eigen Decomposition of a Matrix

Eigenvalue and Eigenvector of a Square Matrix $X \in \mathbb{R}^{d \times d}$

 $X\mathbf{v} = \lambda \mathbf{v}$

Eigen-decomposition of a Matrix

• If eigenvectors of X are linearly independent $X = V\Lambda V^{-1}$

where $\Lambda = \text{diag}(\lambda_1, \ldots, \lambda_d)$ is diagonal

Real and Symmetric Matrices

$$X = V \wedge V^{\top} = \sum_{i=1}^{d} \lambda_i \mathbf{v}_i \mathbf{v}_i^{\top}$$

where *V* is orthogonal matrix ($VV^{\top} = V^{\top}V = I$) and $\Lambda = \text{diag}(\lambda_1, \dots, \lambda_d)$



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Singular Value Decomposition (SVD)

For a matrix $X \in \mathbb{R}^{m \times n}$ with $m \le n$

$$\operatorname{rank}(X) = |\{i : \sigma_i > 0\}|$$

• Compact SVD $X = U_r \Sigma_r V_r^{\top} = \sum_{i=1}^r \sigma_i \mathbf{u}_i \mathbf{v}_i^{\top}$ where $U_r \in \mathbb{R}^{m \times r}$, $\Sigma_r = \text{diag}(\sigma_1, \dots, \sigma_r) \in \mathbb{R}^{r \times r}$, $V_r \in \mathbb{R}^{n \times r}$, $U_r^{\top} U_r = I$, $V_r^{\top} V_r = I$, and $\sigma_i > 0$.

Singular Value Decomposition (SVD)

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$$X = U\Sigma V^{\top} = \sum_{i=1}^{m} \sigma_i \mathbf{u}_i \mathbf{v}_i^{\top}$$

where $U \in \mathbb{R}^{m \times m}$, $\Sigma = \text{diag}(\sigma_1, \dots, \sigma_m) \in \mathbb{R}^{m \times m}$,
 $V \in \mathbb{R}^{n \times m}$, $U^{\top}U = UU^{\top} = I$, $V^{\top}V = I$, and $\sigma_i \ge 0$.

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$$\begin{split} \boldsymbol{X} &= \boldsymbol{U}\boldsymbol{\Sigma}\boldsymbol{V}^{\top} = \sum_{i=1}^{m} \sigma_{i} \mathbf{u}_{i} \mathbf{v}_{i}^{\top} \\ \text{where } \boldsymbol{U} \in \mathbb{R}^{m \times m}, \, \boldsymbol{\Sigma} = \text{diag}(\sigma_{1}, \ldots, \sigma_{m}) \in \mathbb{R}^{m \times m}, \\ \boldsymbol{V} \in \mathbb{R}^{n \times m}, \, \boldsymbol{U}^{\top} \boldsymbol{U} = \boldsymbol{U} \boldsymbol{U}^{\top} = \boldsymbol{I}, \, \boldsymbol{V}^{\top} \boldsymbol{V} = \boldsymbol{I}, \, \text{and} \, \sigma_{i} \geq \boldsymbol{0}. \end{split}$$

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Positive Semi-definite (PSD) Matrices

A symmetric matrix $X \in \mathbb{R}^{d \times d}$ is PSD if

•
$$\mathbf{x}^{\top} X \mathbf{x} \geq \mathbf{0}, \, \forall \mathbf{x} \in \mathbb{R}^d$$

•
$$X = UU^{\top}$$

• all the eigenvalues are nonnegative



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Norm

Vector Norm

•
$$\|\mathbf{x}\|_1 = \sum_{i=1}^d |x_i|, \|\mathbf{x}\|_2 = \sqrt{\sum_{i=1}^d x_i^2}, \|\mathbf{x}\|_{\infty} = \max |x_i|,$$

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Matrix Norm $X = U \Sigma V^{\top}$

- Nuclear Norm: $||X||_* = \sum_{i=1}^n \sigma_i = ||(\sigma_1, ..., \sigma_n)||_1$
- Frobenius norm: $\|X\|_F = \sqrt{\sum_{ij} X_{ij}^2} = \sqrt{\operatorname{trace}(X^\top X)} = \|(\sigma_1, \dots, \sigma_n)\|_2$
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- Rank: rank(X) = $|\{i : \sigma_i > 0\}| = ||(\sigma_1, \dots, \sigma_n)||_0$, which is non-convex



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- Rank: rank(X) = $|\{i : \sigma_i > 0\}| = ||(\sigma_1, \dots, \sigma_n)||_0$, which is non-convex



Questions

Eigen-decomposition versus SVD

For a real and symmetric matrix *A*, what is the difference between its Eigen-decomposition and SVD?



Outline





- Probability and Statistics
- Convex Optimization



Analysis I

- Function
- Continuous
- Differentiable
- Derivative
- Gradient/Subgradient
- Chain rule

The Challenge

How to evaluate the gradient of functions where the variable is a vector or a matrix?

$$f(\mathbf{x}) = \mathbf{w}^\top \mathbf{x}, \quad \nabla f(\mathbf{x}) = \mathbf{w}$$
$$f(\mathbf{x}) = \mathbf{x}^\top A \mathbf{x}, \quad \nabla f(\mathbf{x}) = 2A \mathbf{x}$$



Outline











Probability and Statistics

- Random Variable
- Independent
- Expectation
- Variance/Covariance
- Probability Density Function
- Common Distributions
- Concentration Inequalities



Hoeffding's inequality

Let X_1, \ldots, X_n be independent random variables. Assume that the X_i are almost surely bounded, that is,

$$\Pr(X_i \in [a_i, b_i]) = 1, \ 1 \le i \le n$$

Denote

$$\overline{X} = \frac{1}{n} \sum_{i=1}^{n} X_i$$

Then, we have

$$\Pr\left(\overline{X} - \operatorname{E}[\overline{X}] \ge t\right) \le \exp\left(-\frac{2n^2t^2}{\sum_{i=1}^{n}(b_i - a_i)^2}\right)$$
$$\Pr\left(\overline{X} - \operatorname{E}[\overline{X}] \le -t\right) \le \exp\left(-\frac{2n^2t^2}{\sum_{i=1}^{n}(b_i - a_i)^2}\right)$$

Corollary 1

Assume $b_i - a_i \leq c$. With a probability at least $1 - 2\delta$, we have $-\sqrt{\frac{c}{2n}\log\frac{1}{\delta}} \leq \overline{X} - \mathbb{E}[\overline{X}] \leq \sqrt{\frac{c}{2n}\log\frac{1}{\delta}}$

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Outline











Convex Optimization

- Convexity
- Optimal Solution
- The Lagrange Dual Problem
- KKT Optimality Conditions
- Gradient Descent
- Stochastic Optimization

A good reference is "Stephen Boyd and Lieven Vandenberghe. Convex Optimization, Cambridge University Press, 2004."



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