

Mining Big Data

Lijun Zhang
zlj@nju.edu.cn

Nanjing University, China

December 23, 2015

Outline

- 1 Introduction
 - Big Data
 - Supervised Learning
- 2 Stochastic Optimization
 - Time Reduction
 - Space Reduction
- 3 Distributed Optimization
 - Distributed Gradient Descent
 - ADMM
- 4 Online Learning
 - Full-Information Setting
 - Bandit Setting
- 5 Summary

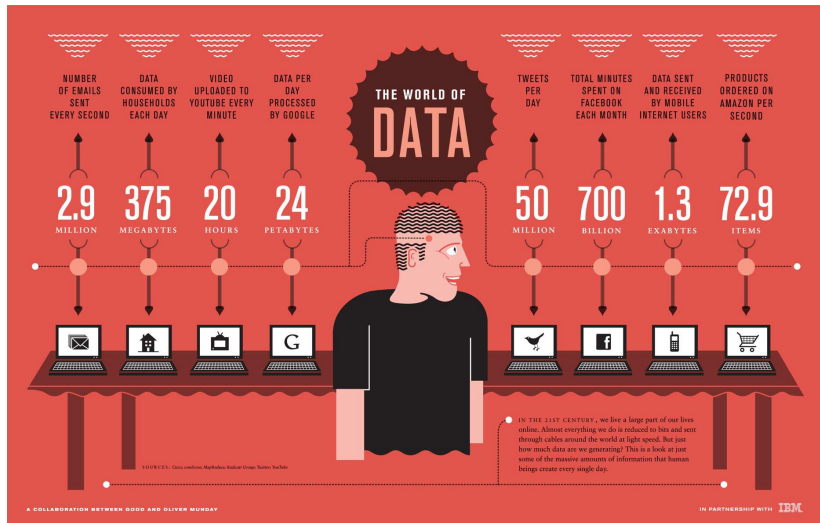


Outline

- 1 Introduction
 - Big Data
 - Supervised Learning
- 2 Stochastic Optimization
 - Time Reduction
 - Space Reduction
- 3 Distributed Optimization
 - Distributed Gradient Descent
 - ADMM
- 4 Online Learning
 - Full-Information Setting
 - Bandit Setting
- 5 Summary



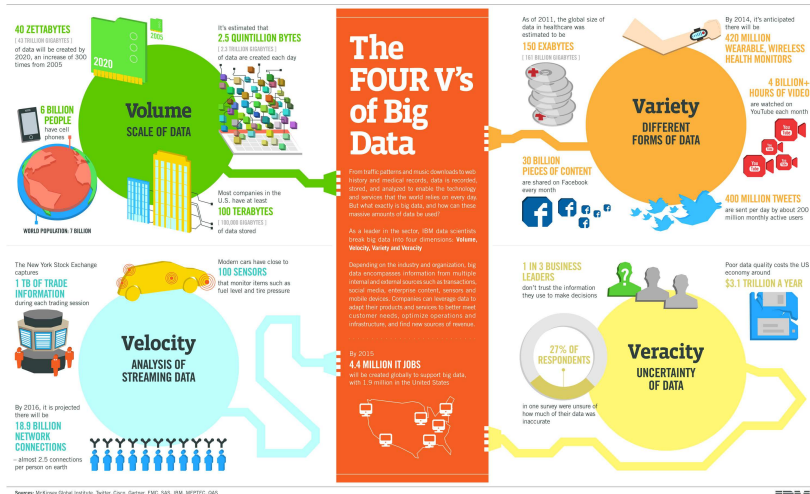
Big Data



<https://infographiclist.files.wordpress.com/2011/09/world-of-data.jpeg>



The Four V's of Big Data



http://www.ibmbigdatahub.com/sites/default/files/infographic_file/4-Vs-of-big-data.jpg

IBM



Outline

- 1 Introduction
 - Big Data
 - Supervised Learning
- 2 Stochastic Optimization
 - Time Reduction
 - Space Reduction
- 3 Distributed Optimization
 - Distributed Gradient Descent
 - ADMM
- 4 Online Learning
 - Full-Information Setting
 - Bandit Setting
- 5 Summary



Supervised Learning (I)

Training

Input

- A set of training data $(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n)$
 - Classification v.s. Regression
 - Batch Setting v.s. Online Setting

Output

- A function $g(\cdot)$ such that $y_i \approx g(\mathbf{x}_i), \forall i$

Testing

Given a testing point $\mathbf{x}$, predict its label by $g(\mathbf{x})$

Assumption

Training and testing data are independent and identically distributed (i.i.d.)



Supervised Learning (I)

Training

Input

- A set of training data $(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n)$
 - Classification v.s. Regression
 - Batch Setting v.s. Online Setting

Output

- A function $g(\cdot)$ such that $y_i \approx g(\mathbf{x}_i), \forall i$

Testing

Given a testing point $\mathbf{x}$, predict its label by $g(\mathbf{x})$

Assumption

Training and testing data are independent and identically distributed (i.i.d.)



Supervised Learning (I)

Training

Input

- A set of training data $(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n)$
 - Classification v.s. Regression
 - Batch Setting v.s. Online Setting

Output

- A function $g(\cdot)$ such that $y_i \approx g(\mathbf{x}_i), \forall i$

Testing

Given a testing point $\mathbf{x}$, predict its label by $g(\mathbf{x})$

Assumption

Training and testing data are independent and identically distributed (**i.i.d.**)



Supervised Learning (II)

Loss Function

Measure the discrepancy between y and $g(\mathbf{x})$

- Binary loss: $\ell(u, v) = \mathbf{1}(uv < 0)$
- Hinge loss: $\ell(u, v) = \max(0, 1 - uv)$
- Squared loss: $\ell(u, v) = (u - v)^2$

Empirical Risk

$$\frac{1}{n} \sum_{i=1}^n \ell(y_i, g(\mathbf{x}_i))$$

Risk

$$\mathbb{E}_{(\mathbf{x}, y)} [\ell(y, g(\mathbf{x}))]$$

Our goal is to minimize the risk instead of empirical risk.



Supervised Learning (II)

Loss Function

Measure the discrepancy between y and $g(\mathbf{x})$

- Binary loss: $\ell(u, v) = \mathbf{1}(uv < 0)$
- Hinge loss: $\ell(u, v) = \max(0, 1 - uv)$
- Squared loss: $\ell(u, v) = (u - v)^2$

Empirical Risk

$$\frac{1}{n} \sum_{i=1}^n \ell(y_i, g(\mathbf{x}_i))$$

Risk

$$\mathbb{E}_{(\mathbf{x}, y)} [\ell(y, g(\mathbf{x}))]$$

Our goal is to minimize the risk instead of empirical risk.



Supervised Learning (II)

Loss Function

Measure the discrepancy between y and $g(\mathbf{x})$

- Binary loss: $\ell(u, v) = \mathbf{1}(uv < 0)$
- Hinge loss: $\ell(u, v) = \max(0, 1 - uv)$
- Squared loss: $\ell(u, v) = (u - v)^2$

Empirical Risk

$$\frac{1}{n} \sum_{i=1}^n \ell(y_i, g(\mathbf{x}_i))$$

Risk

$$\mathbb{E}_{(\mathbf{x}, y)} [\ell(y, g(\mathbf{x}))]$$

Our goal is to minimize the risk instead of empirical risk.



Outline

- 1 Introduction
 - Big Data
 - Supervised Learning
- 2 Stochastic Optimization
 - Time Reduction
 - Space Reduction
- 3 Distributed Optimization
 - Distributed Gradient Descent
 - ADMM
- 4 Online Learning
 - Full-Information Setting
 - Bandit Setting
- 5 Summary



What is Stochastic Optimization? (I)

Definition 1: A Special Objective [Nemirovski et al., 2009]

$$\min_{\mathbf{w} \in \mathcal{W}} f(\mathbf{w}) = \mathbb{E}_{\xi} [\ell(\mathbf{w}, \xi)] = \int_{\Xi} \ell(\mathbf{w}, \xi) dP(\xi)$$

where ξ is a random variable

- It is possible to generate an **i.i.d.** sample $\xi_1, \xi_2, \dots$

Risk Minimization

$$\min_{\mathbf{w} \in \mathcal{W}} f(\mathbf{w}) = \mathbb{E}_{(\mathbf{x}, y)} [\ell(y, \mathbf{x}^T \mathbf{w})]$$

$\ell(\cdot, \cdot)$ is a loss function, e.g., hinge loss $\ell(u, v) = \max(0, 1 - uv)$

- Training data $(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n)$ are **i.i.d.**



What is Stochastic Optimization? (I)

Definition 1: A Special Objective [Nemirovski et al., 2009]

$$\min_{\mathbf{w} \in \mathcal{W}} f(\mathbf{w}) = \mathbb{E}_{\xi} [\ell(\mathbf{w}, \xi)] = \int_{\Xi} \ell(\mathbf{w}, \xi) dP(\xi)$$

where ξ is a random variable

- It is possible to generate an **i.i.d.** sample $\xi_1, \xi_2, \dots$

Risk Minimization

$$\min_{\mathbf{w} \in \mathcal{W}} f(\mathbf{w}) = \mathbb{E}_{(\mathbf{x}, y)} [\ell(y, \mathbf{x}^T \mathbf{w})]$$

$\ell(\cdot, \cdot)$ is a loss function, e.g., hinge loss $\ell(u, v) = \max(0, 1 - uv)$

- Training data $(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n)$ are **i.i.d.**



What is Stochastic Optimization? (II)

Definition 2: A Special Access Model [Hazan and Kale, 2011]

$$\min_{\mathbf{w} \in \mathcal{W}} f(\mathbf{w})$$

- There exists a stochastic **oracle** that produces **unbiased** gradient $\mathbf{m}(\cdot)$

$$\mathbb{E}[\mathbf{m}(\mathbf{w})] = \nabla f(\mathbf{w})$$

Empirical Risk Minimization

$$\min_{\mathbf{w} \in \mathcal{W}} f(\mathbf{w}) = \frac{1}{n} \sum_{i=1}^n \ell(y_i, \mathbf{x}_i^\top \mathbf{w})$$

- Sampling a $(\mathbf{x}_t, y_t)$ from $\{(\mathbf{x}_i, y_i)\}_{i=1}^n$ **uniformly at random**

$$\mathbb{E}[\nabla \ell(y_t, \mathbf{x}_t^\top \mathbf{w})] = \nabla \frac{1}{n} \sum_{i=1}^n \ell(y_i, \mathbf{x}_i^\top \mathbf{w})$$



What is Stochastic Optimization? (II)

Definition 2: A Special Access Model [Hazan and Kale, 2011]

$$\min_{\mathbf{w} \in \mathcal{W}} f(\mathbf{w})$$

- There exists a stochastic **oracle** that produces **unbiased** gradient $\mathbf{m}(\cdot)$

$$\mathbb{E}[\mathbf{m}(\mathbf{w})] = \nabla f(\mathbf{w})$$

Empirical Risk Minimization

$$\min_{\mathbf{w} \in \mathcal{W}} f(\mathbf{w}) = \frac{1}{n} \sum_{i=1}^n \ell(y_i, \mathbf{x}_i^\top \mathbf{w})$$

- Sampling a $(\mathbf{x}_t, y_t)$ from $\{(\mathbf{x}_i, y_i)\}_{i=1}^n$ **uniformly at random**

$$\mathbb{E}[\nabla \ell(y_t, \mathbf{x}_t^\top \mathbf{w})] = \nabla \frac{1}{n} \sum_{i=1}^n \ell(y_i, \mathbf{x}_i^\top \mathbf{w})$$



Outline

- 1 Introduction
 - Big Data
 - Supervised Learning
- 2 Stochastic Optimization
 - Time Reduction
 - Space Reduction
- 3 Distributed Optimization
 - Distributed Gradient Descent
 - ADMM
- 4 Online Learning
 - Full-Information Setting
 - Bandit Setting
- 5 Summary



Time Reduction (I)

Empirical Risk Minimization

$$\min_{\mathbf{w} \in \mathcal{W} \subseteq \mathbb{R}^d} f(\mathbf{w}) = \frac{1}{n} \sum_{i=1}^n \ell(y_i, \mathbf{x}_i^\top \mathbf{w})$$

- n is the number of training data
- d is the dimensionality

Deterministic Optimization—Gradient Descent (GD)

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: $\mathbf{w}'_{t+1} = \mathbf{w}_t - \eta_t \left(\frac{1}{n} \sum_{i=1}^n \nabla \ell(y_i, \mathbf{x}_i^\top \mathbf{w}_t) \right)$
- 3: $\mathbf{w}_{t+1} = \Pi_{\mathcal{W}}(\mathbf{w}'_{t+1})$
- 4: **end for**

The Challenge

- Time complexity per iteration: $O(nd) + O(\text{poly}(d))$



Time Reduction (I)

Empirical Risk Minimization

$$\min_{\mathbf{w} \in \mathcal{W} \subseteq \mathbb{R}^d} f(\mathbf{w}) = \frac{1}{n} \sum_{i=1}^n \ell(y_i, \mathbf{x}_i^\top \mathbf{w})$$

- n is the number of training data
- d is the dimensionality

Deterministic Optimization—Gradient Descent (GD)

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: $\mathbf{w}'_{t+1} = \mathbf{w}_t - \eta_t \left(\frac{1}{n} \sum_{i=1}^n \nabla \ell(y_i, \mathbf{x}_i^\top \mathbf{w}_t) \right)$
- 3: $\mathbf{w}_{t+1} = \Pi_{\mathcal{W}}(\mathbf{w}'_{t+1})$
- 4: **end for**

The Challenge

- Time complexity per iteration: $O(nd) + O(\text{poly}(d))$



Time Reduction (I)

Empirical Risk Minimization

$$\min_{\mathbf{w} \in \mathcal{W} \subseteq \mathbb{R}^d} f(\mathbf{w}) = \frac{1}{n} \sum_{i=1}^n \ell(y_i, \mathbf{x}_i^\top \mathbf{w})$$

- n is the number of training data
- d is the dimensionality

Deterministic Optimization—Gradient Descent (GD)

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: $\mathbf{w}'_{t+1} = \mathbf{w}_t - \eta_t \left(\frac{1}{n} \sum_{i=1}^n \nabla \ell(y_i, \mathbf{x}_i^\top \mathbf{w}_t) \right)$
- 3: $\mathbf{w}_{t+1} = \Pi_{\mathcal{W}}(\mathbf{w}'_{t+1})$
- 4: **end for**

The Challenge

- Time complexity per iteration: $O(nd) + O(\text{poly}(d))$



Time Reduction (II)

Empirical Risk Minimization

$$\min_{\mathbf{w} \in \mathcal{W} \subseteq \mathbb{R}^d} f(\mathbf{w}) = \frac{1}{n} \sum_{i=1}^n \ell(y_i, \mathbf{x}_i^\top \mathbf{w})$$

Stochastic Optimization—Stochastic Gradient Descent (SGD)

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: Sample a training example $(\mathbf{x}_t, y_t)$ **uniformly at random**
- 3: $\mathbf{w}'_{t+1} = \mathbf{w}_t - \eta_t \nabla \ell(y_t, \mathbf{x}_t^\top \mathbf{w}_t)$
- 4: $\mathbf{w}_{t+1} = \Pi_{\mathcal{W}}(\mathbf{w}'_{t+1})$
- 5: **end for**

The Advantage—Time Reduction

- Time complexity per iteration: $O(d) + O(\text{poly}(d))$



Time Reduction (II)

Empirical Risk Minimization

$$\min_{\mathbf{w} \in \mathcal{W} \subseteq \mathbb{R}^d} f(\mathbf{w}) = \frac{1}{n} \sum_{i=1}^n \ell(y_i, \mathbf{x}_i^\top \mathbf{w})$$

Stochastic Optimization—Stochastic Gradient Descent (SGD)

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: Sample a training example $(\mathbf{x}_t, y_t)$ **uniformly at random**
- 3: $\mathbf{w}'_{t+1} = \mathbf{w}_t - \eta_t \nabla \ell(y_t, \mathbf{x}_t^\top \mathbf{w}_t)$
- 4: $\mathbf{w}_{t+1} = \Pi_{\mathcal{W}}(\mathbf{w}'_{t+1})$
- 5: **end for**

The Advantage—Time Reduction

- Time complexity per iteration: $O(d) + O(\text{poly}(d))$



Time Reduction (II)

Empirical Risk Minimization

$$\min_{\mathbf{w} \in \mathcal{W} \subseteq \mathbb{R}^d} f(\mathbf{w}) = \frac{1}{n} \sum_{i=1}^n \ell(y_i, \mathbf{x}_i^\top \mathbf{w})$$

Stochastic Optimization—Stochastic Gradient Descent (SGD)

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: Sample a training example $(\mathbf{x}_t, y_t)$ **uniformly at random**
- 3: $\mathbf{w}'_{t+1} = \mathbf{w}_t - \eta_t \nabla \ell(y_t, \mathbf{x}_t^\top \mathbf{w}_t)$
- 4: $\mathbf{w}_{t+1} = \Pi_{\mathcal{W}}(\mathbf{w}'_{t+1})$
- 5: **end for**

The Advantage—Time Reduction

- Time complexity per iteration: $O(d) + O(\text{poly}(d))$



Outline

- 1 Introduction
 - Big Data
 - Supervised Learning
- 2 Stochastic Optimization
 - Time Reduction
 - Space Reduction
- 3 Distributed Optimization
 - Distributed Gradient Descent
 - ADMM
- 4 Online Learning
 - Full-Information Setting
 - Bandit Setting
- 5 Summary



Space Reduction (I)

Nuclear Norm Regularized Optimization over Matrices

$$\min_{W \in \mathbb{R}^{m \times n}} F(W) = f(W) + \lambda \|W\|_*$$

- Matrix completion, multi-class classification
- Both m and n can be very **large**
- The optimal solution W_* is **low-rank**

Collaborative Filtering—Matrix Completion

$$\min_{W \in \mathbb{R}^{m \times n}} F(W) = \sum_{(i,j) \in \Omega} (W_{ij} - M_{ij})^2 + \lambda \|W\|_*$$

- There are m users and n items
- $M \in \mathbb{R}^{m \times n}$ is the underlying user-item rating matrix
- Ω is the set of observed indices



Space Reduction (I)

Nuclear Norm Regularized Optimization over Matrices

$$\min_{W \in \mathcal{W} \subseteq \mathbb{R}^{m \times n}} F(W) = f(W) + \lambda \|W\|_*$$

- Matrix completion, multi-class classification
- Both m and n can be very **large**
- The optimal solution W_* is **low-rank**

Collaborative Filtering—Matrix Completion

$$\min_{W \in \mathbb{R}^{m \times n}} F(W) = \sum_{(i,j) \in \Omega} (W_{ij} - M_{ij})^2 + \lambda \|W\|_*$$

- There are m users and n items
- $M \in \mathbb{R}^{m \times n}$ is the underlying user-item rating matrix
- Ω is the set of observed indices



Space Reduction (II)

Nuclear Norm Regularized Optimization over Matrices

$$\min_{W \in \mathcal{W} \subseteq \mathbb{R}^{m \times n}} F(W) = f(W) + \lambda \|W\|_*$$

- Matrix completion, multi-class classification
- Both m and n can be very **large**
- The optimal solution W_* is **low-rank**

Deterministic Optimization—Gradient Descent (GD)

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: $W'_{t+1} = W_t - \eta_t \nabla F(W_t)$
- 3: $W_{t+1} = \Pi_{\mathcal{W}}(W'_{t+1})$
- 4: **end for**

The Challenge

- Space complexity per iteration: $O(mn)$



Space Reduction (II)

Nuclear Norm Regularized Optimization over Matrices

$$\min_{W \in \mathcal{W} \subseteq \mathbb{R}^{m \times n}} F(W) = f(W) + \lambda \|W\|_*$$

- Matrix completion, multi-class classification
- Both m and n can be very **large**
- The optimal solution W_* is **low-rank**

Deterministic Optimization—Gradient Descent (GD)

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: $W'_{t+1} = W_t - \eta_t \nabla F(W_t)$
- 3: $W_{t+1} = \Pi_{\mathcal{W}}(W'_{t+1})$
- 4: **end for**

The Challenge

- Space complexity per iteration: $O(mn)$



Space Reduction (II)

Nuclear Norm Regularized Optimization over Matrices

$$\min_{W \in \mathcal{W} \subseteq \mathbb{R}^{m \times n}} F(W) = f(W) + \lambda \|W\|_*$$

- Matrix completion, multi-class classification
- Both m and n can be very **large**
- The optimal solution W_* is **low-rank**

Deterministic Optimization—Gradient Descent (GD)

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: $W'_{t+1} = W_t - \eta_t \nabla F(W_t)$
- 3: $W_{t+1} = \Pi_{\mathcal{W}}(W'_{t+1})$
- 4: **end for**

The Challenge

- Space complexity per iteration: $O(mn)$



Space Reduction (III)

Nuclear Norm Regularized Optimization over Matrices

$$\min_{W \in \mathbb{R}^{m \times n}} F(W) = f(W) + \lambda \|W\|_*$$

Stochastic Proximal Gradient Descent (SPGD)

[Zhang et al., 2015]

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: Generate a **low-rank** stochastic gradient $\hat{G}_t$ of $f(\cdot)$ at W_t
- 3:

$$W_{t+1} = \operatorname{argmin}_{W \in \mathbb{R}^{m \times n}} \frac{1}{2} \left\| W - (W_t - \eta_t \hat{G}_t) \right\|_F^2 + \eta_t \lambda \|W\|_*$$

- 4: **end for**
- 5: **return** W_{T+1}

The Advantage—Space Reduction

- Space complexity per iteration is **low**: $O((m+n)r)$



Space Reduction (III)

Nuclear Norm Regularized Optimization over Matrices

$$\min_{W \in \mathbb{R}^{m \times n}} F(W) = f(W) + \lambda \|W\|_*$$

Stochastic Proximal Gradient Descent (SPGD)

[Zhang et al., 2015]

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: Generate a **low-rank** stochastic gradient $\hat{G}_t$ of $f(\cdot)$ at W_t

$$W_{t+1} = \operatorname{argmin}_{W \in \mathbb{R}^{m \times n}} \frac{1}{2} \|W - (W_t - \eta_t \hat{G}_t)\|_F^2 + \eta_t \lambda \|W\|_*$$

- 4: **end for**
- 5: **return** W_{T+1}

The Advantage—Space Reduction

- Space complexity per iteration is **low**: $O((m+n)r)$



Space Reduction (III)

Nuclear Norm Regularized Optimization over Matrices

$$\min_{W \in \mathbb{W} \subset \mathbb{R}^{m \times n}} F(W) = f(W) + \lambda \|W\|_*$$

Stochastic Proximal Gradient Descent (SPGD)

[Zhang et al., 2015]

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: Generate a **low-rank** stochastic gradient $\hat{G}_t$ of $f(\cdot)$ at W_t

$$W_{t+1} = \operatorname{argmin}_{W \in \mathbb{R}^{m \times n}} \frac{1}{2} \left\| W - (W_t - \eta_t \hat{G}_t) \right\|_F^2 + \eta_t \lambda \|W\|_*$$

- 4: **end for**
- 5: **return** W_{T+1}

The Advantage—*Space Reduction*

- Space complexity per iteration is **low**: $O((m+n)r)$



Limitations

Iteration Complexity

The number of iterations T to ensure

$$f(\mathbf{w}_T) - \min_{\mathbf{w} \in \Omega} f(\mathbf{w}) \leq \epsilon$$

Iteration Complexity of GD and SGD

	Convex & Smooth	Strongly Convex & Smooth
GD	$O\left(\frac{1}{\sqrt{\epsilon}}\right)$	$O\left(\sqrt{\kappa} \log \frac{1}{\epsilon}\right)$
SGD	$O\left(\frac{1}{\epsilon^2}\right)$	$O\left(\frac{1}{\mu\epsilon}\right)$

Total Time Complexity of GD and SGD

	Convex & Smooth	Strongly Convex & Smooth
GD	$O\left(\frac{n}{\sqrt{\epsilon}}\right)$	$O\left(n\sqrt{\kappa} \log \frac{1}{\epsilon}\right)$
SGD	$O\left(\frac{1}{\epsilon^2}\right)$	$O\left(\frac{1}{\mu\epsilon}\right)$



Limitations

Iteration Complexity

The number of iterations T to ensure

$$f(\mathbf{w}_T) - \min_{\mathbf{w} \in \Omega} f(\mathbf{w}) \leq \epsilon$$

Iteration Complexity of GD and SGD

	Convex & Smooth	Strongly Convex & Smooth
GD	$O\left(\frac{1}{\sqrt{\epsilon}}\right)$	$O\left(\sqrt{\kappa} \log \frac{1}{\epsilon}\right)$
SGD	$O\left(\frac{1}{\epsilon^2}\right)$	$O\left(\frac{1}{\mu\epsilon}\right)$

Total Time Complexity of GD and SGD

	Convex & Smooth	Strongly Convex & Smooth
GD	$O\left(\frac{n}{\sqrt{\epsilon}}\right)$	$O\left(n\sqrt{\kappa} \log \frac{1}{\epsilon}\right)$
SGD	$O\left(\frac{1}{\epsilon^2}\right)$	$O\left(\frac{1}{\mu\epsilon}\right)$



Limitations

Iteration Complexity

The number of iterations T to ensure

$$f(\mathbf{w}_T) - \min_{\mathbf{w} \in \Omega} f(\mathbf{w}) \leq \epsilon$$

Iteration Complexity of GD and SGD $\epsilon = 10^{-6}$

	Convex & Smooth	Strongly Convex & Smooth
GD	$O\left(\frac{1}{\sqrt{\epsilon}}\right) \quad 10^3$	$O\left(\sqrt{\kappa} \log \frac{1}{\epsilon}\right) \quad 6\sqrt{\kappa}$
SGD	$O\left(\frac{1}{\epsilon^2}\right) \quad 10^{12}$	$O\left(\frac{1}{\mu\epsilon}\right) \quad \frac{10^6}{\mu}$

Total Time Complexity of GD and SGD

	Convex & Smooth	Strongly Convex & Smooth
GD	$O\left(\frac{n}{\sqrt{\epsilon}}\right)$	$O\left(n\sqrt{\kappa} \log \frac{1}{\epsilon}\right)$
SGD	$O\left(\frac{1}{\epsilon^2}\right)$	$O\left(\frac{1}{\mu\epsilon}\right)$



Limitations

Iteration Complexity

The number of iterations T to ensure

$$f(\mathbf{w}_T) - \min_{\mathbf{w} \in \Omega} f(\mathbf{w}) \leq \epsilon$$

Iteration Complexity of GD and SGD $\epsilon = 10^{-6}$

	Convex & Smooth	Strongly Convex & Smooth
GD	$O\left(\frac{1}{\sqrt{\epsilon}}\right)$ 10^3	$O\left(\sqrt{\kappa} \log \frac{1}{\epsilon}\right)$ $6\sqrt{\kappa}$
SGD	$O\left(\frac{1}{\epsilon^2}\right)$ 10^{12}	$O\left(\frac{1}{\mu\epsilon}\right)$ $\frac{10^6}{\mu}$

Total Time Complexity of GD and SGD

	Convex & Smooth	Strongly Convex & Smooth
GD	$O\left(\frac{n}{\sqrt{\epsilon}}\right)$	$O\left(n\sqrt{\kappa} \log \frac{1}{\epsilon}\right)$
SGD	$O\left(\frac{1}{\epsilon^2}\right)$	$O\left(\frac{1}{\mu\epsilon}\right)$



Limitations

Iteration Complexity

The number of iterations T to ensure

$$f(\mathbf{w}_T) - \min_{\mathbf{w} \in \Omega} f(\mathbf{w}) \leq \epsilon$$

Iteration Complexity of GD and SGD $\epsilon = 10^{-6}$

	Convex & Smooth	Strongly Convex & Smooth
GD	$O\left(\frac{1}{\sqrt{\epsilon}}\right) \quad 10^3$	$O\left(\sqrt{\kappa} \log \frac{1}{\epsilon}\right) \quad 6\sqrt{\kappa}$
SGD	$O\left(\frac{1}{\epsilon^2}\right) \quad 10^{12}$	$O\left(\frac{1}{\mu\epsilon}\right) \quad \frac{10^6}{\mu}$

Total Time Complexity of GD and SGD $\epsilon = 10^{-6}$

	Convex & Smooth	Strongly Convex & Smooth
GD	$O\left(\frac{n}{\sqrt{\epsilon}}\right) \quad 10^3 n$	$O\left(n\sqrt{\kappa} \log \frac{1}{\epsilon}\right) \quad 6n\sqrt{\kappa}$
SGD	$O\left(\frac{1}{\epsilon^2}\right) \quad 10^{12}$	$O\left(\frac{1}{\mu\epsilon}\right) \quad \frac{10^6}{\mu}$



Outline

- 1 Introduction
 - Big Data
 - Supervised Learning
- 2 Stochastic Optimization
 - Time Reduction
 - Space Reduction
- 3 Distributed Optimization
 - Distributed Gradient Descent
 - ADMM
- 4 Online Learning
 - Full-Information Setting
 - Bandit Setting
- 5 Summary

Introduction (I)

Empirical Risk Minimization in Distributed Setting

$$\min_{\mathbf{w} \in \mathcal{W}} f(\mathbf{w}) = \sum_{j=1}^k \sum_{i=1}^{n_j} \ell(y_i^j, \mathbf{w}^\top \mathbf{x}_i^j)$$

- $(\mathbf{x}_1^j, y_1^j) \dots (\mathbf{x}_{n_j}^j, y_{n_j}^j)$ are training data in the j -th machine


 $(\mathbf{x}_1^1, y_1^1)$
 $\dots$
 $(\mathbf{x}_{n_1}^1, y_{n_1}^1)$

 $(\mathbf{x}_1^2, y_1^2)$
 $\dots$
 $(\mathbf{x}_{n_2}^2, y_{n_2}^2)$
 $\dots$

 $(\mathbf{x}_1^k, y_1^k)$
 $\dots$
 $(\mathbf{x}_{n_k}^k, y_{n_k}^k)$


Introduction (II)

General Distributed Optimization

$$\min_{\mathbf{w} \in \mathcal{W}} f(\mathbf{w}) = \sum_{j=1}^k f_j(\mathbf{w})$$

- For empirical risk minimization, we have

$$f_j(\mathbf{w}) = \sum_{i=1}^{n_j} \ell(y_i^j, \mathbf{w}^\top \mathbf{x}_i^j)$$

 $f_1(\mathbf{w})$  $f_2(\mathbf{w})$

...

 $f_k(\mathbf{w})$ 

Outline

- 1 Introduction
 - Big Data
 - Supervised Learning
- 2 Stochastic Optimization
 - Time Reduction
 - Space Reduction
- 3 Distributed Optimization
 - Distributed Gradient Descent
 - ADMM
- 4 Online Learning
 - Full-Information Setting
 - Bandit Setting
- 5 Summary



Distributed Gradient Descent

Gradient Descent

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: $\mathbf{w}'_{t+1} = \mathbf{w}_t - \eta_t \left(\sum_{j=1}^k \nabla f_j(\mathbf{w}_t) \right)$
- 3: $\mathbf{w}_{t+1} = \Pi_{\mathcal{W}}(\mathbf{w}'_{t+1})$
- 4: **end for**

Distributed Gradient Descent

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: Server: send $\mathbf{w}_t$ to each worker
- 3: Each worker j : calculate $\nabla f_j(\mathbf{w}_t)$ and send it to server
- 4: Server: $\mathbf{w}'_{t+1} = \mathbf{w}_t - \eta_t \left(\sum_{j=1}^k \nabla f_j(\mathbf{w}_t) \right)$
- 5: Server: $\mathbf{w}_{t+1} = \Pi_{\mathcal{W}}(\mathbf{w}'_{t+1})$
- 6: **end for**



Distributed Gradient Descent

Gradient Descent

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: $\mathbf{w}'_{t+1} = \mathbf{w}_t - \eta_t \left(\sum_{j=1}^k \nabla f_j(\mathbf{w}_t) \right)$
- 3: $\mathbf{w}_{t+1} = \Pi_{\mathcal{W}}(\mathbf{w}'_{t+1})$
- 4: **end for**

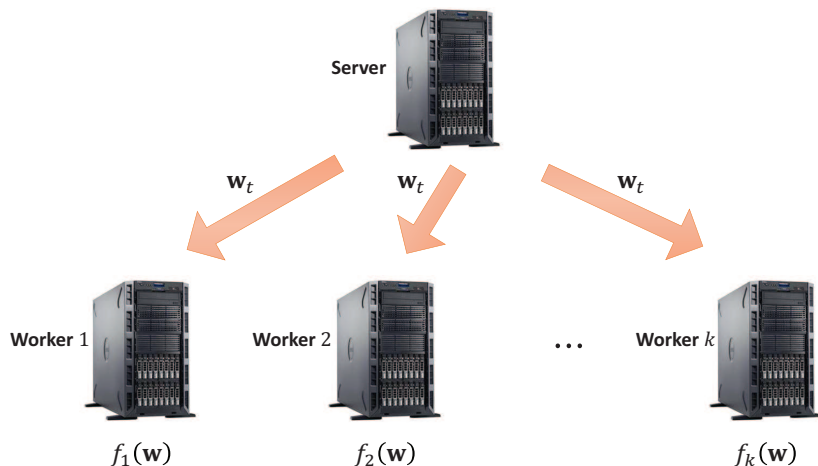
Distributed Gradient Descent

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: Server: send $\mathbf{w}_t$ to each worker
- 3: Each worker j : calculate $\nabla f_j(\mathbf{w}_t)$ and send it to server
- 4: Server: $\mathbf{w}'_{t+1} = \mathbf{w}_t - \eta_t \left(\sum_{j=1}^k \nabla f_j(\mathbf{w}_t) \right)$
- 5: Server: $\mathbf{w}_{t+1} = \Pi_{\mathcal{W}}(\mathbf{w}'_{t+1})$
- 6: **end for**



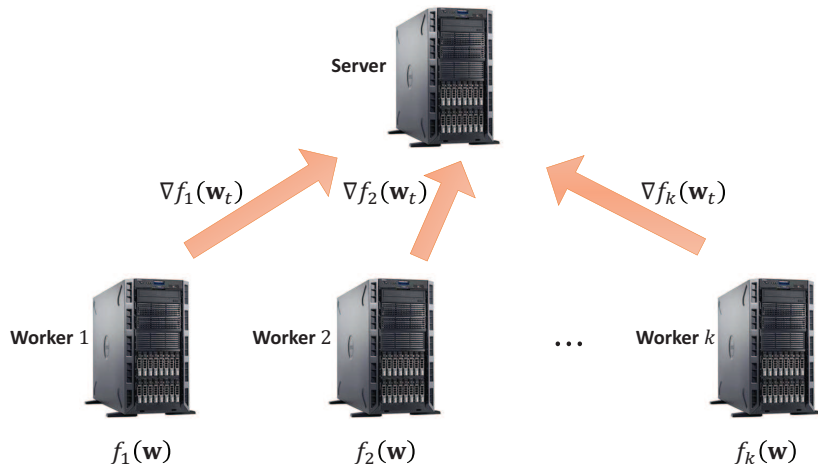
Step 1

Server: send $\mathbf{w}_t$ to each worker



Step 2

Each worker j : calculate $\nabla f_j(\mathbf{w}_t)$ and send it to server



Steps 3 and 4

- Server: $\mathbf{w}'_{t+1} = \mathbf{w}_t - \eta_t \left(\sum_{j=1}^k \nabla f_j(\mathbf{w}_t) \right)$
- Server: $\mathbf{w}_{t+1} = \Pi_{\mathcal{W}}(\mathbf{w}'_{t+1})$

Server



$$\mathbf{w}'_{t+1} = \mathbf{w}_t - \eta_t \left(\sum_{j=1}^k \nabla f_j(\mathbf{w}_t) \right)$$
$$\mathbf{w}_{t+1} = \Pi_{\mathcal{W}}(\mathbf{w}'_{t+1})$$



Outline

- 1 Introduction
 - Big Data
 - Supervised Learning
- 2 Stochastic Optimization
 - Time Reduction
 - Space Reduction
- 3 Distributed Optimization
 - Distributed Gradient Descent
 - **ADMM**
- 4 Online Learning
 - Full-Information Setting
 - Bandit Setting
- 5 Summary

Reformulation of the Distributed Optimization (I)

General Distributed Optimization

$$\min_{\mathbf{w} \in \mathcal{W}} f(\mathbf{w}) = \sum_{j=1}^k f_j(\mathbf{w})$$

Global Consensus Problem

$$\min_{\mathbf{y} \in \mathcal{W}, \{\mathbf{w}_j = \mathbf{y}\}_{j=1}^k} \sum_{j=1}^k f_j(\mathbf{w}_j)$$

The Lagrangian

$$\max_{\lambda_1, \dots, \lambda_k} \min_{\mathbf{y} \in \mathcal{W}, \mathbf{w}_1, \dots, \mathbf{w}_k} \sum_{j=1}^k f_j(\mathbf{w}_j) - \langle \lambda_j, \mathbf{w}_j - \mathbf{y} \rangle$$



Reformulation of the Distributed Optimization (I)

General Distributed Optimization

$$\min_{\mathbf{w} \in \mathcal{W}} f(\mathbf{w}) = \sum_{j=1}^k f_j(\mathbf{w})$$

Global Consensus Problem

$$\min_{\mathbf{y} \in \mathcal{W}, \{\mathbf{w}_j = \mathbf{y}\}_{j=1}^k} \sum_{j=1}^k f_j(\mathbf{w}_j)$$

The Lagrangian

$$\max_{\lambda_1, \dots, \lambda_k} \min_{\mathbf{y} \in \mathcal{W}, \mathbf{w}_1, \dots, \mathbf{w}_k} \sum_{j=1}^k f_j(\mathbf{w}_j) - \langle \lambda_j, \mathbf{w}_j - \mathbf{y} \rangle$$



Reformulation of the Distributed Optimization (I)

General Distributed Optimization

$$\min_{\mathbf{w} \in \mathcal{W}} f(\mathbf{w}) = \sum_{j=1}^k f_j(\mathbf{w})$$

Global Consensus Problem

$$\min_{\mathbf{y} \in \mathcal{W}, \{\mathbf{w}_j = \mathbf{y}\}_{j=1}^k} \sum_{j=1}^k f_j(\mathbf{w}_j)$$

The Lagrangian

$$\max_{\lambda_1, \dots, \lambda_k} \min_{\mathbf{y} \in \mathcal{W}, \mathbf{w}_1, \dots, \mathbf{w}_k} \sum_{j=1}^k f_j(\mathbf{w}_j) - \langle \lambda_j, \mathbf{w}_j - \mathbf{y} \rangle$$



Reformulation of the Distributed Optimization (II)

The Augmented Lagrangian [Roux et al., 2012]

$$\max_{\lambda_1, \dots, \lambda_k} \min_{\mathbf{y} \in \mathcal{W}, \mathbf{w}_1, \dots, \mathbf{w}_k} \sum_{j=1}^k f_j(\mathbf{w}_j) - \langle \lambda_j, \mathbf{w}_j - \mathbf{y} \rangle + \frac{1}{2\gamma} \|\mathbf{w}_j - \mathbf{y}\|_2^2$$

Alternating Direction Method of Multipliers (ADMM)

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: Server: send $\mathbf{y}^t$ and λ_j^t to worker $j = 1, \dots, k$
- 3: Each worker j : calculate $\mathbf{w}_j^{t+1}$ and send it to server

$$\mathbf{w}_j^{t+1} = \underset{\mathbf{w}}{\operatorname{argmin}} f_j(\mathbf{w}) + \frac{1}{2\gamma} \|\mathbf{y}^t + \gamma \lambda_j^t - \mathbf{w}\|_2^2, j = 1, \dots, k$$

- 4: Server: $\mathbf{y}^{t+1} = \Pi_{\mathcal{W}} \left(\frac{1}{k} \sum_{j=1}^k (\mathbf{w}_j^{t+1} - \gamma \lambda_j^t) \right)$
- 5: Server: $\lambda_j^{t+1} = \lambda_j^t + \frac{1}{\gamma} (\mathbf{y}^{t+1} - \mathbf{w}_j^{t+1}), j = 1, \dots, k$
- 6: **end for**



Reformulation of the Distributed Optimization (II)

The Augmented Lagrangian [Roux et al., 2012]

$$\max_{\lambda_1, \dots, \lambda_k} \min_{\mathbf{y} \in \mathcal{W}, \mathbf{w}_1, \dots, \mathbf{w}_k} \sum_{j=1}^k f_j(\mathbf{w}_j) - \langle \lambda_j, \mathbf{w}_j - \mathbf{y} \rangle + \frac{1}{2\gamma} \|\mathbf{w}_j - \mathbf{y}\|_2^2$$

Alternating Direction Method of Multipliers (ADMM)

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: Server: send $\mathbf{y}^t$ and λ_j^t to worker $j = 1, \dots, k$
- 3: Each worker j : calculate $\mathbf{w}_j^{t+1}$ and send it to server

$$\mathbf{w}_j^{t+1} = \underset{\mathbf{w}}{\operatorname{argmin}} f_j(\mathbf{w}) + \frac{1}{2\gamma} \|\mathbf{y}^t + \gamma \lambda_j^t - \mathbf{w}\|_2^2, j = 1, \dots, k$$

- 4: Server: $\mathbf{y}^{t+1} = \Pi_{\mathcal{W}} \left(\frac{1}{k} \sum_{j=1}^k (\mathbf{w}_j^{t+1} - \gamma \lambda_j^t) \right)$
- 5: Server: $\lambda_j^{t+1} = \lambda_j^t + \frac{1}{\gamma} \left(\mathbf{y}^{t+1} - \mathbf{w}_j^{t+1} \right), j = 1, \dots, k$
- 6: **end for**



Reformulation of the Distributed Optimization (II)

The Augmented Lagrangian [Roux et al., 2012]

$$\max_{\lambda_1, \dots, \lambda_k} \min_{\mathbf{y} \in \mathcal{W}, \mathbf{w}_1, \dots, \mathbf{w}_k} \sum_{j=1}^k f_j(\mathbf{w}_j) - \langle \lambda_j, \mathbf{w}_j - \mathbf{y} \rangle + \frac{1}{2\gamma} \|\mathbf{w}_j - \mathbf{y}\|_2^2$$

Alternating Direction Method of Multipliers (ADMM)

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: Server: send $\mathbf{y}^t$ and λ_j^t to worker $j = 1, \dots, k$
- 3: Each worker j : calculate $\mathbf{w}_j^{t+1}$ and send it to server

$$\mathbf{w}_j^{t+1} = \underset{\mathbf{w}}{\operatorname{argmin}} f_j(\mathbf{w}) + \frac{1}{2\gamma} \|\mathbf{y}^t + \gamma \lambda_j^t - \mathbf{w}\|_2^2, j = 1, \dots, k$$

- 4: Server: $\mathbf{y}^{t+1} = \Pi_{\mathcal{W}} \left(\frac{1}{k} \sum_{j=1}^k (\mathbf{w}_j^{t+1} - \gamma \lambda_j^t) \right)$
- 5: Server: $\lambda_j^{t+1} = \lambda_j^t + \frac{1}{\gamma} \left(\mathbf{y}^{t+1} - \mathbf{w}_j^{t+1} \right), j = 1, \dots, k$
- 6: **end for**



Reformulation of the Distributed Optimization (II)

The Augmented Lagrangian [Roux et al., 2012]

$$\max_{\lambda_1, \dots, \lambda_k} \min_{\mathbf{y} \in \mathcal{W}, \mathbf{w}_1, \dots, \mathbf{w}_k} \sum_{j=1}^k f_j(\mathbf{w}_j) - \langle \lambda_j, \mathbf{w}_j - \mathbf{y} \rangle + \frac{1}{2\gamma} \|\mathbf{w}_j - \mathbf{y}\|_2^2$$

Alternating Direction Method of Multipliers (ADMM)

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: Server: send $\mathbf{y}^t$ and λ_j^t to worker $j = 1, \dots, k$
- 3: Each worker j : calculate $\mathbf{w}_j^{t+1}$ and send it to server

$$\mathbf{w}_j^{t+1} = \underset{\mathbf{w}}{\operatorname{argmin}} f_j(\mathbf{w}) + \frac{1}{2\gamma} \|\mathbf{y}^t + \gamma \lambda_j^t - \mathbf{w}\|_2^2, j = 1, \dots, k$$

- 4: Server: $\mathbf{y}^{t+1} = \Pi_{\mathcal{W}} \left(\frac{1}{k} \sum_{j=1}^k (\mathbf{w}_j^{t+1} - \gamma \lambda_j^t) \right)$
- 5: Server: $\lambda_j^{t+1} = \lambda_j^t + \frac{1}{\gamma} \left(\mathbf{y}^{t+1} - \mathbf{w}_j^{t+1} \right), j = 1, \dots, k$
- 6: **end for**



Reformulation of the Distributed Optimization (II)

The Augmented Lagrangian [Roux et al., 2012]

$$\max_{\lambda_1, \dots, \lambda_k} \min_{\mathbf{y} \in \mathcal{W}, \mathbf{w}_1, \dots, \mathbf{w}_k} \sum_{j=1}^k f_j(\mathbf{w}_j) - \langle \lambda_j, \mathbf{w}_j - \mathbf{y} \rangle + \frac{1}{2\gamma} \|\mathbf{w}_j - \mathbf{y}\|_2^2$$

Alternating Direction Method of Multipliers (ADMM)

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: Server: send $\mathbf{y}^t$ and λ_j^t to worker $j = 1, \dots, k$
- 3: Each worker j : calculate $\mathbf{w}_j^{t+1}$ and send it to server

$$\mathbf{w}_j^{t+1} = \underset{\mathbf{w}}{\operatorname{argmin}} f_j(\mathbf{w}) + \frac{1}{2\gamma} \|\mathbf{y}^t + \gamma \lambda_j^t - \mathbf{w}\|_2^2, j = 1, \dots, k$$

- 4: Server: $\mathbf{y}^{t+1} = \Pi_{\mathcal{W}} \left(\frac{1}{k} \sum_{j=1}^k (\mathbf{w}_j^{t+1} - \gamma \lambda_j^t) \right)$
- 5: Server: $\lambda_j^{t+1} = \lambda_j^t + \frac{1}{\gamma} \left(\mathbf{y}^{t+1} - \mathbf{w}_j^{t+1} \right), j = 1, \dots, k$
- 6: **end for**



Reformulation of the Distributed Optimization (II)

The Augmented Lagrangian [Roux et al., 2012]

$$\max_{\lambda_1, \dots, \lambda_k} \min_{\mathbf{y} \in \mathcal{W}, \mathbf{w}_1, \dots, \mathbf{w}_k} \sum_{j=1}^k f_j(\mathbf{w}_j) - \langle \lambda_j, \mathbf{w}_j - \mathbf{y} \rangle + \frac{1}{2\gamma} \|\mathbf{w}_j - \mathbf{y}\|_2^2$$

Alternating Direction Method of Multipliers (ADMM)

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: Server: send $\mathbf{y}^t$ and λ_j^t to worker $j = 1, \dots, k$
- 3: Each worker j : calculate $\mathbf{w}_j^{t+1}$ and send it to server

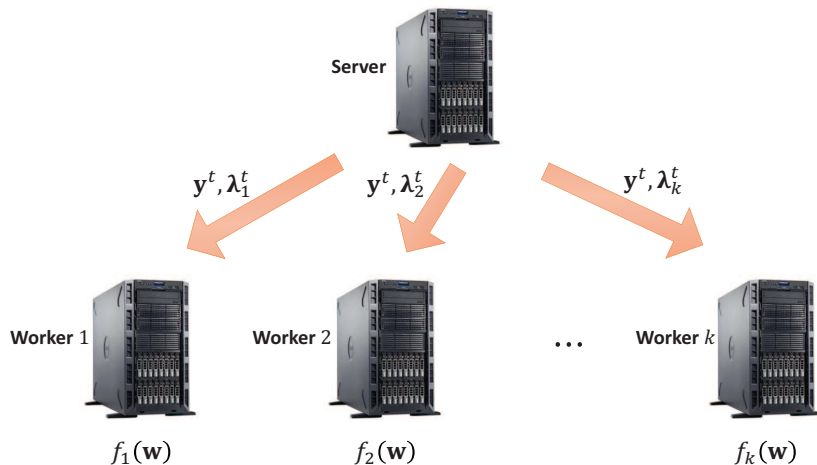
$$\mathbf{w}_j^{t+1} = \underset{\mathbf{w}}{\operatorname{argmin}} f_j(\mathbf{w}) + \frac{1}{2\gamma} \|\mathbf{y}^t + \gamma \lambda_j^t - \mathbf{w}\|_2^2, j = 1, \dots, k$$

- 4: Server: $\mathbf{y}^{t+1} = \Pi_{\mathcal{W}} \left(\frac{1}{k} \sum_{j=1}^k (\mathbf{w}_j^{t+1} - \gamma \lambda_j^t) \right)$
- 5: Server: $\lambda_j^{t+1} = \lambda_j^t + \frac{1}{\gamma} \left(\mathbf{y}^{t+1} - \mathbf{w}_j^{t+1} \right), j = 1, \dots, k$
- 6: **end for**



Step 1

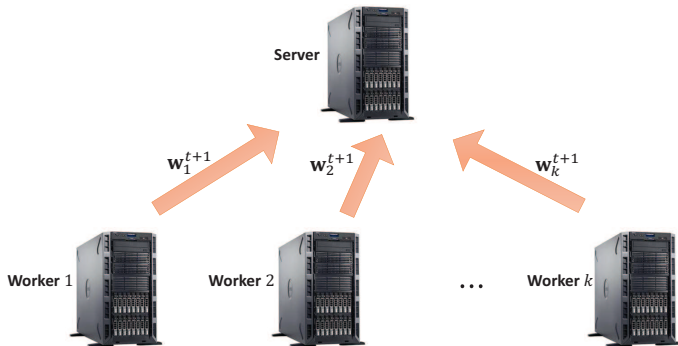
Server: send $\mathbf{y}^t$ and λ_j^t to worker $j = 1, \dots, k$



Step 2

Each worker j : calculate $\mathbf{w}_j^{t+1}$ and send it to server

$$\mathbf{w}_j^{t+1} = \underset{\mathbf{w}}{\operatorname{argmin}} f_j(\mathbf{w}) + \frac{1}{2\gamma} \|\mathbf{y}^t + \gamma \boldsymbol{\lambda}_j^t - \mathbf{w}\|_2^2, j = 1, \dots, k$$



$$\mathbf{w}_1^{t+1} = \underset{\mathbf{w}}{\operatorname{argmin}} f_1(\mathbf{w}) + \frac{1}{2\gamma} \|\mathbf{y}^t + \gamma \boldsymbol{\lambda}_1^t - \mathbf{w}\|_2^2 \quad \mathbf{w}_k^{t+1} = \underset{\mathbf{w}}{\operatorname{argmin}} f_k(\mathbf{w}) + \frac{1}{2\gamma} \|\mathbf{y}^t + \gamma \boldsymbol{\lambda}_k^t - \mathbf{w}\|_2^2$$



Steps 3 and 4

- Server: $\mathbf{y}^{t+1} = \Pi_{\mathcal{W}} \left(\frac{1}{k} \sum_{j=1}^k (\mathbf{w}_j^{t+1} - \gamma \lambda_j^t) \right)$
- Server: $\lambda_j^{t+1} = \lambda_j^t + \frac{1}{\gamma} \left(\mathbf{y}^{t+1} - \mathbf{w}_j^{t+1} \right), j = 1, \dots, k$

Server

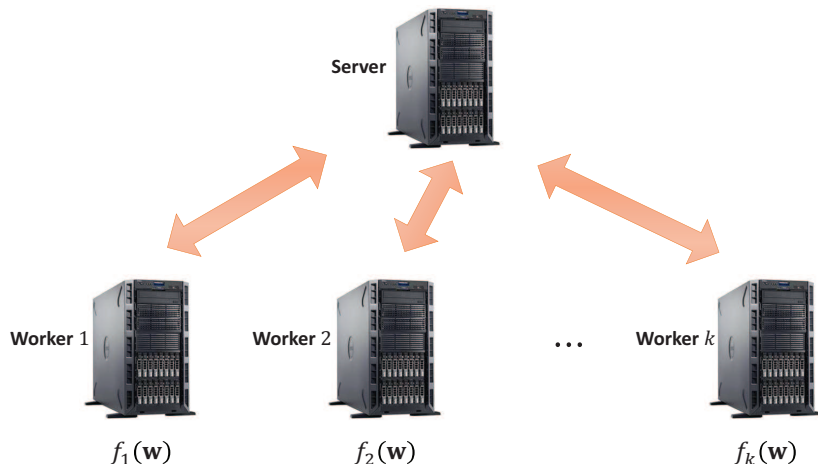


$$\mathbf{y}^{t+1} = \Pi_{\mathcal{W}} \left(\frac{1}{k} \sum_{j=1}^k (\mathbf{w}_j^{t+1} - \gamma \lambda_j^t) \right)$$

$$\lambda_j^{t+1} = \lambda_j^t + \frac{1}{\gamma} (\mathbf{y}^{t+1} - \mathbf{w}_j^{t+1}), j = 1 \dots, k$$

Challenges of Distributed Optimization

- Communication
- Synchronization



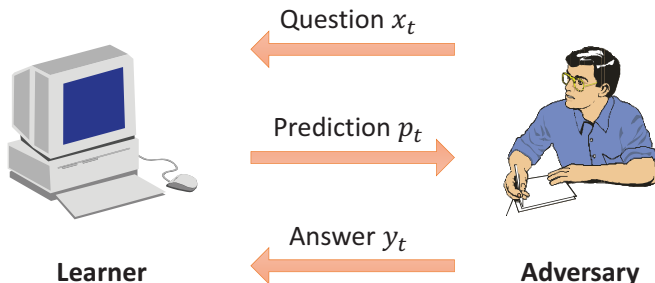
Outline

- 1 Introduction
 - Big Data
 - Supervised Learning
- 2 Stochastic Optimization
 - Time Reduction
 - Space Reduction
- 3 Distributed Optimization
 - Distributed Gradient Descent
 - ADMM
- 4 Online Learning
 - Full-Information Setting
 - Bandit Setting
- 5 Summary

Online Learning (I)

Online Learning [Shalev-Shwartz, 2011]

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: Receive a question $x_t \in \mathcal{X}$
- 3: Predict $p_t \in \mathcal{D}$
- 4: Receive true answer $y_t \in \mathcal{Y}$
- 5: Suffer loss $\ell(y_t, p_t)$
- 6: **end for**



Online Learning (II)

Online Learning [Shalev-Shwartz, 2011]

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: Receive a question $\mathbf{x}_t \in \mathcal{X}$
- 3: Predict $p_t \in \mathcal{D}$
- 4: Receive true answer $y_t \in \mathcal{Y}$
- 5: Suffer loss $\ell(y_t, p_t)$
- 6: **end for**

An Example—Online Classification

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: Receive a question $\mathbf{x}_t \in \mathcal{X} \subseteq \mathbb{R}^d$
- 3: Predict $p_t \in \mathcal{D} = \{0, 1\}$
- 4: Receive true answer $y_t \in \mathcal{Y} = \{0, 1\}$
- 5: Suffer loss $\ell(y_t, p_t) = |y_t - p_t|$
- 6: **end for**



Online Learning (III)

Online Learning [Shalev-Shwartz, 2011]

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: Receive a question $x_t \in \mathcal{X}$
- 3: Predict $p_t \in \mathcal{D}$
- 4: Receive true answer $y_t \in \mathcal{Y}$
- 5: Suffer loss $\ell(y_t, p_t)$
- 6: **end for**

Cumulative Loss

$$\text{Cumulative Loss} = \sum_{t=1}^T \ell(y_t, p_t)$$



Online Learning (VI)

Online Learning [Shalev-Shwartz, 2011]

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: Receive a question $x_t \in \mathcal{X}$
- 3: Predict $p_t \in \mathcal{D}$
- 4: Receive true answer $y_t \in \mathcal{Y}$
- 5: Suffer loss $\ell(y_t, p_t)$
- 6: **end for**

Regret with respect to a hypothesis class $\mathcal{H}$

$$\text{Regret} = \sum_{t=1}^T \ell(y_t, p_t) - \min_{h \in \mathcal{H}} \sum_{t=1}^T \ell(y_t, h(x_t))$$

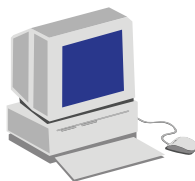
$$h : \mathcal{X} \mapsto \mathcal{D}$$



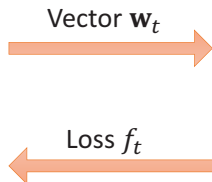
Online Convex Optimization (I)

Online Convex Optimization [Shalev-Shwartz, 2011]

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: Predict a vector $\mathbf{w}_t \in \mathcal{W} \subseteq \mathbb{R}^d$
- 3: Receive a convex loss function $f_t : \mathcal{W} \rightarrow \mathbb{R}$
- 4: Suffer loss $f_t(\mathbf{w}_t)$
- 5: **end for**



Learner



Adversary

Online Convex Optimization (II)

Online Convex Optimization [Shalev-Shwartz, 2011]

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: Predict a vector $\mathbf{w}_t \in \mathcal{W} \subseteq \mathbb{R}^d$
- 3: Receive a convex loss function $f_t : \mathcal{W} \rightarrow \mathbb{R}$
- 4: Suffer loss $f_t(\mathbf{w}_t)$
- 5: **end for**

An Example—Online SVM

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: Predict a vector $\mathbf{w}_t \in \mathcal{W} \subseteq \mathbb{R}^d$
- 3: Receive a training instance $(\mathbf{x}_t, y_t)$
- 4: Suffer loss $f_t(\mathbf{w}_t) = \ell(y_t, \mathbf{x}_t^\top \mathbf{w}_t) = \max(0, 1 - y_t \mathbf{x}_t^\top \mathbf{w}_t)$
- 5: **end for**



Online Convex Optimization (III)

Online Convex Optimization [Shalev-Shwartz, 2011]

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: Predict a vector $\mathbf{w}_t \in \mathcal{W} \subseteq \mathbb{R}^d$
- 3: Receive a convex loss function $f_t : \mathcal{W} \rightarrow \mathbb{R}$
- 4: Suffer loss $f_t(\mathbf{w}_t)$
- 5: **end for**

Regret

$$\text{Regret} = \sum_{t=1}^T f_t(\mathbf{w}_t) - \min_{\mathbf{w} \in \mathcal{W}} \sum_{t=1}^T f_t(\mathbf{w})$$



Outline

- 1 Introduction
 - Big Data
 - Supervised Learning
- 2 Stochastic Optimization
 - Time Reduction
 - Space Reduction
- 3 Distributed Optimization
 - Distributed Gradient Descent
 - ADMM
- 4 Online Learning
 - Full-Information Setting
 - Bandit Setting
- 5 Summary



Online Gradient Descent

Full-Information Setting

The learner observes not only $f_t(\mathbf{w}_t)$ but also $f_t(\cdot)$.

Online Gradient Descent [Zinkevich, 2003, Hazan et al., 2007]

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: Predict a vector $\mathbf{w}_t \in \mathcal{W} \subseteq \mathbb{R}^d$
- 3: Receive a convex loss function $f_t : \mathcal{W} \rightarrow \mathbb{R}$
- 4: Suffer loss $f_t(\mathbf{w}_t)$
- 5: $\mathbf{w}_{t+1} = \mathbf{w}_t - \eta_t \nabla f_t(\mathbf{w}_t)$
- 6: **end for**

Regret Bound [Zinkevich, 2003, Hazan et al., 2007]

$$\text{Regret} = \sum_{t=1}^T f_t(\mathbf{w}_t) - \min_{\mathbf{w} \in \mathcal{W}} \sum_{t=1}^T f_t(\mathbf{w}) = O\left(\sqrt{T}\right) \text{ or } O(\log T)$$



Online Gradient Descent

Full-Information Setting

The learner observes not only $f_t(\mathbf{w}_t)$ but also $f_t(\cdot)$.

Online Gradient Descent [Zinkevich, 2003, Hazan et al., 2007]

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: Predict a vector $\mathbf{w}_t \in \mathcal{W} \subseteq \mathbb{R}^d$
- 3: Receive a convex loss function $f_t : \mathcal{W} \rightarrow \mathbb{R}$
- 4: Suffer loss $f_t(\mathbf{w}_t)$
- 5: $\mathbf{w}_{t+1} = \mathbf{w}_t - \eta_t \nabla f_t(\mathbf{w}_t)$
- 6: **end for**

Regret Bound [Zinkevich, 2003, Hazan et al., 2007]

$$\text{Regret} = \sum_{t=1}^T f_t(\mathbf{w}_t) - \min_{\mathbf{w} \in \mathcal{W}} \sum_{t=1}^T f_t(\mathbf{w}) = O\left(\sqrt{T}\right) \text{ or } O(\log T)$$



Online Gradient Descent

Full-Information Setting

The learner observes not only $f_t(\mathbf{w}_t)$ but also $f_t(\cdot)$.

Online Gradient Descent [Zinkevich, 2003, Hazan et al., 2007]

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: Predict a vector $\mathbf{w}_t \in \mathcal{W} \subseteq \mathbb{R}^d$
- 3: Receive a convex loss function $f_t : \mathcal{W} \rightarrow \mathbb{R}$
- 4: Suffer loss $f_t(\mathbf{w}_t)$
- 5: $\mathbf{w}_{t+1} = \mathbf{w}_t - \eta_t \nabla f_t(\mathbf{w}_t)$
- 6: **end for**

Regret Bound [Zinkevich, 2003, Hazan et al., 2007]

$$\text{Regret} = \sum_{t=1}^T f_t(\mathbf{w}_t) - \min_{\mathbf{w} \in \mathcal{W}} \sum_{t=1}^T f_t(\mathbf{w}) = O\left(\sqrt{T}\right) \text{ or } O(\log T)$$



Outline

- 1 Introduction
 - Big Data
 - Supervised Learning
- 2 Stochastic Optimization
 - Time Reduction
 - Space Reduction
- 3 Distributed Optimization
 - Distributed Gradient Descent
 - ADMM
- 4 Online Learning
 - Full-Information Setting
 - **Bandit Setting**
- 5 Summary



Bandit Setting

Bandit Setting

The learner only observes not only $f_t(\mathbf{w}_t)$.

Generation Process of the Loss Functions

- Stochastic: $f_1, \dots, f_t$ are **i.i.d. sampled**
- Adversarial
 - Oblivious: f_t is **independent** of $\mathbf{w}_1, \dots, \mathbf{w}_{t-1}$
 - Nonoblivious: f_t may **depend** on $\mathbf{w}_1, \dots, \mathbf{w}_{t-1}$

Types of the Loss Functions

- Convex
- Linear
- Multi-armed Bandit



Bandit Setting

Bandit Setting

The learner only observes not only $f_t(\mathbf{w}_t)$.

Generation Process of the Loss Functions

- Stochastic: $f_1, \dots, f_t$ are **i.i.d. sampled**
- Adversarial
 - Oblivious: f_t is **independent** of $\mathbf{w}_1, \dots, \mathbf{w}_{t-1}$
 - Nonoblivious: f_t may **depend** on $\mathbf{w}_1, \dots, \mathbf{w}_{t-1}$

Types of the Loss Functions

- Convex
- Linear
- Multi-armed Bandit



Bandit Setting

Bandit Setting

The learner only observes not only $f_t(\mathbf{w}_t)$.

Generation Process of the Loss Functions

- Stochastic: $f_1, \dots, f_t$ are **i.i.d. sampled**
- Adversarial
 - Oblivious: f_t is **independent** of $\mathbf{w}_1, \dots, \mathbf{w}_{t-1}$
 - Nonoblivious: f_t may **depend** on $\mathbf{w}_1, \dots, \mathbf{w}_{t-1}$

Types of the Loss Functions

- Convex
- Linear
- Multi-armed Bandit



Multi-armed Bandit



<http://blog.mynaweb.com/wp-content/uploads/2013/02/Bandits.png>



Stochastic Multi-armed Bandit

Setting

- There are K arms
- Successive pulls of arm i yield rewards $X_1^i, X_2^i, \dots$
 - Those rewards are **i.i.d.** according to an unknown distribution D_i with **unknown** mean μ_i

The Learning Process

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: pull arm $i \in [K]$
- 3: Receive reward X^i sampled from distribution $\mathcal{D}_i$
- 4: **end for**

How to maximize the rewards?

Always pull arm $i = \operatorname{argmax}_{i \in [K]} \mu_i$



Stochastic Multi-armed Bandit

Setting

- There are K arms
- Successive pulls of arm i yield rewards $X_1^i, X_2^i, \dots$
 - Those rewards are **i.i.d.** according to an unknown distribution D_i with **unknown** mean μ_i

The Learning Process

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: pull arm $i \in [K]$
- 3: Receive reward X^i sampled from distribution $\mathcal{D}_i$
- 4: **end for**

How to maximize the rewards?

Always pull arm $i = \operatorname{argmax}_{i \in [K]} \mu_i$



Stochastic Multi-armed Bandit

Setting

- There are K arms
- Successive pulls of arm i yield rewards $X_1^i, X_2^i, \dots$
 - Those rewards are **i.i.d.** according to an unknown distribution D_i with **unknown** mean μ_i

The Learning Process

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: pull arm $i \in [K]$
- 3: Receive reward X^i sampled from distribution $\mathcal{D}_i$
- 4: **end for**

How to maximize the rewards?

Always pull arm $i = \operatorname{argmax}_{i \in [K]} \mu_i$



Exploitation-Exploration Dilemma

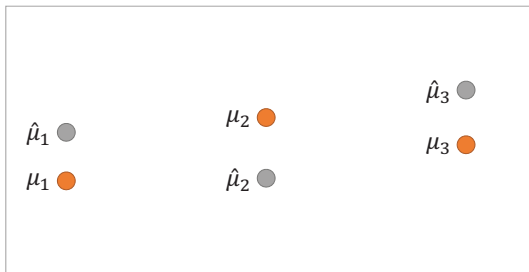
A Naive Algorithm

Exploration

- 1 Pull each arm $m = 100$ times
- 2 Calculate the estimated mean $\hat{\mu}_i$ each arm i

Exploitation

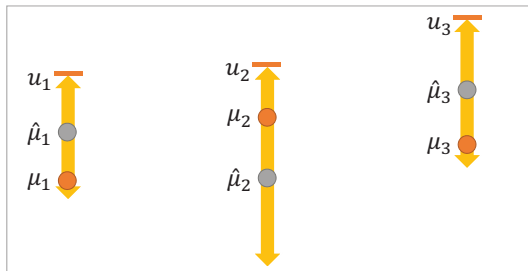
- 1 Always pull arm $i = \operatorname{argmax}_{i \in [K]} \hat{\mu}_i$



Upper Confidence Bounds (I)

Exploitation-Exploration Tradeoff by Upper Confidence Bounds (UCB) [Auer et al., 2002]

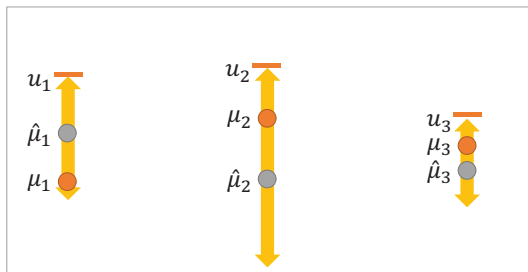
- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: Pull arm $i = \operatorname{argmax}_{i \in [K]} u_i$ (WHP, $u_i \geq \mu_i$)
- 3: Receive reward X^i sampled from distribution $\mathcal{D}_i$
- 4: Update the upper bound u_i for arm i
- 5: **end for**



Upper Confidence Bounds (II)

Exploitation-Exploration Tradeoff by Upper Confidence Bounds (UCB) [Auer et al., 2002]

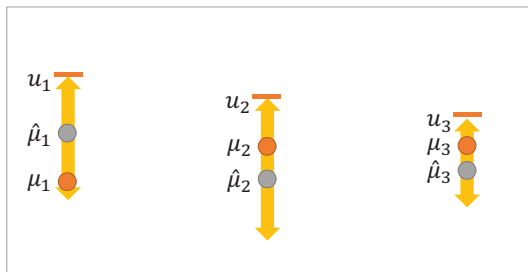
- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: Pull arm $i = \operatorname{argmax}_{i \in [K]} u_i$ (WHP, $u_i \geq \mu_i$)
- 3: Receive reward X^i sampled from distribution $\mathcal{D}_i$
- 4: Update the upper bound u_i for arm i
- 5: **end for**



Upper Confidence Bounds (III)

Exploitation-Exploration Tradeoff by Upper Confidence Bounds (UCB) [Auer et al., 2002]

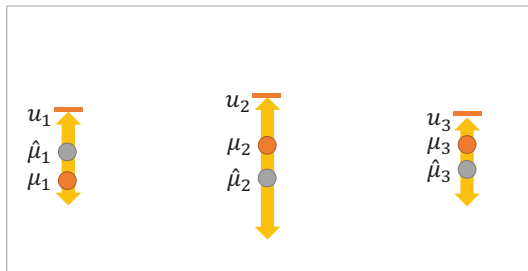
- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: Pull arm $i = \operatorname{argmax}_{i \in [K]} u_i$ (WHP, $u_i \geq \mu_i$)
- 3: Receive reward X^i sampled from distribution $\mathcal{D}_i$
- 4: Update the upper bound u_i for arm i
- 5: **end for**



Upper Confidence Bounds (IV)

Exploitation-Exploration Tradeoff by Upper Confidence Bounds (UCB) [Auer et al., 2002]

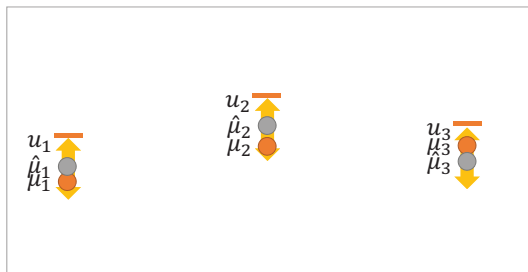
- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: Pull arm $i = \operatorname{argmax}_{i \in [K]} u_i$ (WHP, $u_i \geq \mu_i$)
- 3: Receive reward X^i sampled from distribution $\mathcal{D}_i$
- 4: Update the upper bound u_i for arm i
- 5: **end for**



Upper Confidence Bounds (V)

Exploitation-Exploration Tradeoff by Upper Confidence Bounds (UCB) [Auer et al., 2002]

- 1: **for** $t = 1, 2, \dots, T$ **do**
- 2: Pull arm $i = \operatorname{argmax}_{i \in [K]} u_i$ (WHP, $u_i \geq \mu_i$)
- 3: Receive reward X^i sampled from distribution $\mathcal{D}_i$
- 4: Update the upper bound u_i for arm i
- 5: **end for**



Outline

- 1 Introduction
 - Big Data
 - Supervised Learning
- 2 Stochastic Optimization
 - Time Reduction
 - Space Reduction
- 3 Distributed Optimization
 - Distributed Gradient Descent
 - ADMM
- 4 Online Learning
 - Full-Information Setting
 - Bandit Setting
- 5 Summary



Summary

Stochastic Optimization

- Stochastic Gradient Descent (SGD)—*Time Reduction*
- Stochastic Proximal Gradient Descent (SPGD)—*Space Reduction*

Distributed Optimization

- Distributed Gradient Descent
- Alternating Direction Method of Multipliers (ADMM)

Online Learning

- Full-Information Setting—Online Gradient Descent
- Bandit Setting—Exploitation-Exploration Dilemma



Reference I



Auer, P., Cesa-Bianchi, N., and Fischer, P. (2002).
Finite-time analysis of the multiarmed bandit problem.
Machine Learning, 47(2-3):235–256.



Hazan, E., Agarwal, A., and Kale, S. (2007).
Logarithmic regret algorithms for online convex optimization.
Machine Learning, 69(2-3):169–192.



Hazan, E. and Kale, S. (2011).
Beyond the regret minimization barrier: an optimal algorithm for stochastic strongly-convex optimization.
In Proceedings of the 24th Annual Conference on Learning Theory, pages 421–436.



Nemirovski, A., Juditsky, A., Lan, G., and Shapiro, A. (2009).
Robust stochastic approximation approach to stochastic programming.
SIAM Journal on Optimization, 19(4):1574–1609.



Roux, N. L., Schmidt, M., and Bach, F. (2012).
A stochastic gradient method with an exponential convergence rate for finite training sets.
In Advances in Neural Information Processing Systems 25, pages 2672–2680.

Reference II



Shalev-Shwartz, S. (2011).

Online learning and online convex optimization.

Foundations and Trends in Machine Learning, 4(2):107–194.



Zhang, L., Yang, T., Jin, R., and Zhou, Z.-H. (2015).

Stochastic proximal gradient descent for nuclear norm regularization.

ArXiv e-prints, arXiv:1511.01664.



Zinkevich, M. (2003).

Online convex programming and generalized infinitesimal gradient ascent.

In *Proceedings of the 20th International Conference on Machine Learning*, pages 928–936.

